

## **Features:**

SiRF starIII high performance GPS Chip Set

Very high sensitivity (Tracking Sensitivity: -159 dBm)

Extremely fast TTFF (Time To First Fix) at low signal level

Compact size (30mm \* 28 mm \* 4.6mm) suitable for space-sensitive application

Support NMEA 0183 and SiRF binary protocol

## **Specification:**

### **General**

Chipset	SiRF Star III
Frequency	L1, 1575.42 MHz
C/A code	1.023 MHz chip rate
Channels	20 channel all-in-view tracking
Sensitivity	-159 dBm

### **Accuracy**

Position	10 meters, 2D RMS 5 meters, 2D RMS, WAAS enabled
Velocity	0.1 m/s
Time	1us synchronized to GPS time

### **Datum**

Default	WGS-84
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### **Acquisition Time**

Reacquisition	0.1 sec., average
Hot start	1 sec., average
Warm start	38 sec., average
Cold start	42 sec., average

### **Dynamic Conditions**

Altitude	18,000 meters (60,000 feet) max
Velocity	515 meters /second (1000 knots) max
Acceleration	Less than 4g
Jerk	20m/sec **3

### **Power**

Main power input	3.3V +- 5% DC input
Power consumption	25mA (Continuous mode)

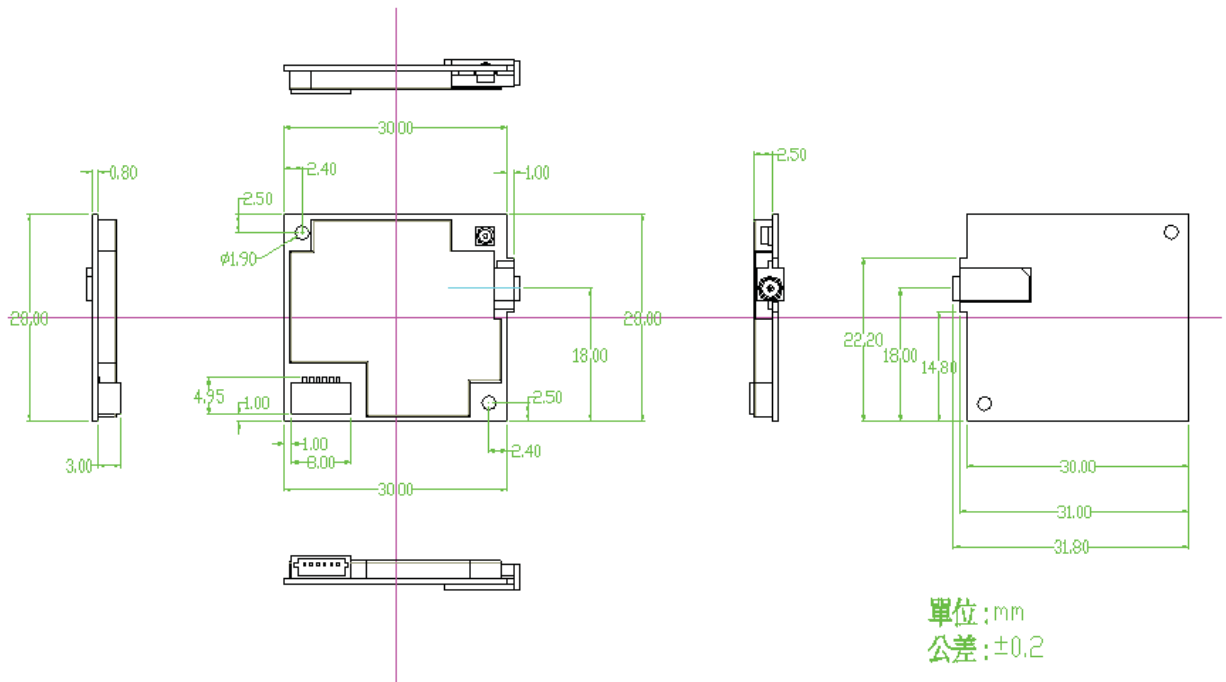
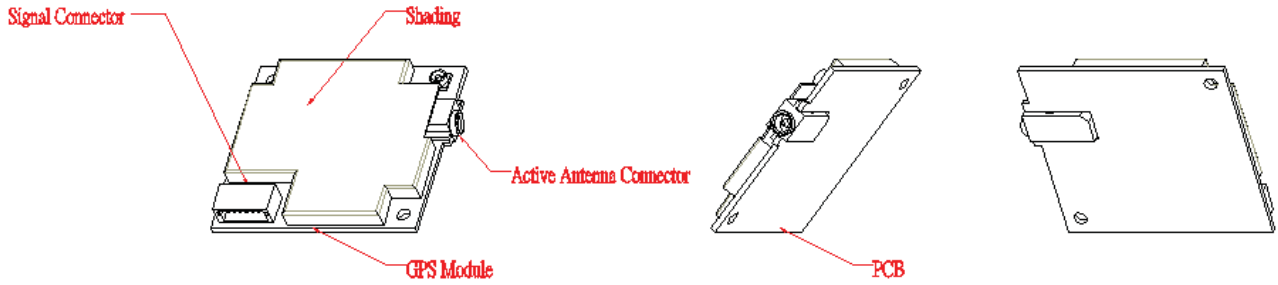
### **Interface**

Dimension	30mm * 28mm * 4.6mm
Baud rate	4,800 to 57,600 bps adjustable
Output message	SiRF binary or NMEA 0183 GGA, GSA, GSV, RMC, VTG, GLL

## Environmental

Operating Temp -40°C to +85°C

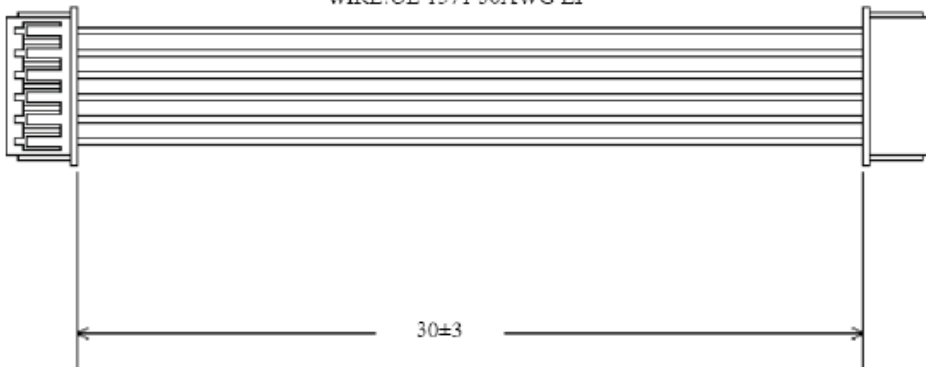
## Pin Assignment & Dimension



HOUSING:TH1001HN0-06

TERMINAL:TH1001TPO-A

WIRE:UL 1571 30AWG LF



Unit: mm

# Pin description

## Power input):

This is the main DC supply for a 3.3V +/- 5% DC input power module board.

## \* GPS-VBAT (Backup battery):

This is the battery backup input that powers the SRAM and RTC when main power is removed. Typical current draw is 15uA. Without an external backup battery, the module/engine board will execute a cold start after every turn on. To achieve the faster start-up offered by a hot or warm start, a battery backup must be connected. The battery voltage should be between 2.0v and 5.0v.

## \* GPS-LED:

User can use this I/O pin for special function.

For example, on/off LED

## \* GPS-TX:

This is the main transmits channel for outputting navigation and measurement data to user's navigation software or user written software.

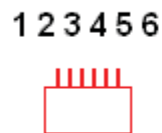
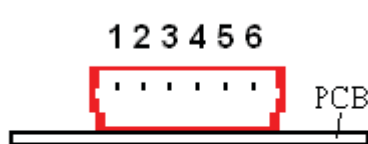
Output TTL level, 0V ~ 2.85V

## \* GPS-RX:

This is the main receive channel for receiving software commands to the engine board from SiRFdemo software or from user written software.

## \* GND:

GND provides the ground for the engine board. Connect all grounds.



PIN	NAME
PIN 1	VDD
PIN 2	GND
PIN 3	GPS-TX
PIN 4	GPS-RX
PIN 5	GPS-LED
PIN 6	GPS-VBAT